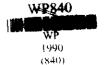
THREAT BARGAINING PROBLEMS WITH INCOMPLETE INFORMATION AND CORRELATED BELIEFS

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N.P. No. 840 January 1990

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ABSTRACT

In this paper we provide a general framework for studying threat bargaining games with incomplete information and correlated beliefs. In this framework we obtain a characterization of the Kalai-Smorodinsky solution without any monotonicity assumption. The approach adds a dose of realism to the already existing literature on threat bargaining games.

1. <u>Introduction</u>

In many arbitration problems, the parties involved are fully aware of the true characteristics of the rival, but the procedure involved is one where each party makes a report on its status—quo position to the arbitrator, who on the basis of such a statement must arrive at a mutually acceptable decision. Further the arbitrator is unaware of the true characteristics of the players. Such situations abound in reality, where it is not the lack of information on the part of the players, but on the part of the arbitrator, which leads to strategic non cooperative behaviour. Such situations can be modelled as threat bargaining problems, as discussed in Lahiri [1988, 1989 a,b];

An additional complication to such problems was considered in Lahiri [1989 c], where each player has a belief regarding the acceptationality to his epponent of an arbitrated butcome, which can be summarized by a probability distribution. Hence coupled with the strategic behaviour of the players in determining the final outcome of arbitration, there is an uncertainty about the solution being acceptable to the opponent. However, in Lahiri [1989 c], it was assumed that each player's belief about an outcome being acceptable to his opponent depended earely on what the opponent received and was not influenced by what the player himself was getting. Such beliefs are naturally uncorrelated.

In this paper we desume that the beliefs are generally correlated. Throughout we desume that the parameters determining the arbitrated outcome are known to the players. However, the arbitrator is unaware of the true status—quo point, and it is this ignorance which results in the strategic behaviour of the players. Arbitration proceeds on the basis of the stated value of the status—quo point. We show here, that if the conditional distribution of the beliefs follow a certain specified form, then the only bargaining solution compatible with truthful revelation of the status—quo point is the Kalai—Smorodinsky [1975] bargaining solution.

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2. Definitions :

In a pure bargaining problem between a group of two participants there is a set of feasible outcomes, any one of which will result if it is specified by the unanimous agreement of all participants. In the event that no unanimous agreement is reached, a given disagreement outcome obtains, we shall assume that the utility space or the set of possible payoffs is R² i.e. a two person bargaining problem is a pair (H,d) of a subset H of R² and of a point deh. H is the feasible set, and d is the disagreement (or threat) point.

The class of bargaining problems we consider is given by the following definition:

Definition 1 :- The pair $\Gamma = (H,d)$ is a two-person fixed threat bargaining game if $H \subseteq R^2$ is compact, convex, comprehensive with non-empty interior, $d \in H$, and H contains at least one element u such that u > d. (Note: $H \subseteq R^2$ is said to be comprehensive if $y \in R^2$, x > y > d for some $x \in H$ implies $y \in H$).

Definition 2 :- The set of two-person fixed threat bargaining games is denoted W.

For the purpose of this paper we define a solution to bargaining problems in W as follows:

Definition 3 :- A solution is a function $F : W \rightarrow R^2_+$ satisfying

- (i) F (H,d) CH + (H,d) CW (fm sibility)
- (ii) $y \in H$, $y \nearrow F(H,d)$ implies y = F(H,d) (Pareto optimality)

(iv) If
$$(a_1, a_2) > > 0$$
, $(b_1, b_2) \in \mathbb{R}^2$, $H' = \{y \in \mathbb{R}^2 / y_1 = a_1 x_1 + b_1, i = 1, 2, y = (y_1, y_2), x = (x_1, x_2) \in H\}$ and $d_1 = a_1 d_1 + b_1$, $i = 1, 2$, $d' = (d_1, d_2)$, then $f_1(H, d') = a_1 f_1(H, d) + b_1$, $i = 1, 2$.

(Independence with respect to affine utility transformations)

The conditions we impose on a solution to bargaining problems are standard and are satisfied by the more well known solutions to bargaining problems (e.g. Nash (1950), Kalai-Smorodinsky (1975)).

We now make an assumption which is satisfied by most familiar solutions to bargaining problems and which will be required significantly by us.

Assumption (FUD) :- Let (H,d)
$$\in$$
 W and P(H_d) = $\{(x_1,x_2) \in H/x = (x_1,x_2), x_1, x_2\}$

Then $\forall (x_1,x_2) \in P(H_d)$, $d_1 \geqslant d_1 \geqslant d_1$, or $d_2 \geqslant d_2$ such that

(i)
$$F(H; d_1, d_2) = (x_1, x_2)$$

or (ii)
$$f(H; d_1, d_2) = (x_1, x_2)$$

(fullness through unilateral deviations).

This assumption requires that unilateral deviation from the given disagreement payoffs yield any Pareto Optimal and individually rational outcome. As mentioned earlier this property is satisfied by all the more well known solutions to bargaining problems, including some of those which may not satisfy some of the conditions of Definition 3 (e.g. the <u>Proportional Solution</u> of Kalai [1977]).

Our analysis requires the notion of a true bargaining problem, which in view of the above and following Anbar and Kalai (1978) may be defined as follows:

Definition 4:- A true bargaining problem H is a compact, convex subset of the unit square containing (0,0), (1,0) and (0,1).

The interpretation of such a bargaining game is that the <u>true</u> disagreement point of the players have been set equal to (0,0) and the game has been normalized in such a way that the utility demands of the players belong to the closed interval [0,1]. Let us call the set of all true bargaining problems W.

Every member $H \in W$ defines uniquely a monotone non-increasing concave function $M_H : [0,1] \rightarrow [0,1]$ by $M_H(x_1) = \max \{x_2/(x_1,x_2) \in H\}$. Conversely every monotone non-increasing concave function $M : [0,1] \rightarrow [0,1]$ such that $M : [0,1] \rightarrow [0,1]$. For every such function $M : [0,1] \rightarrow [0,1]$ by $M^{-1}(x_2) = \max \{x_1/(x_1,x_2) \in H_M\}$.

Let $G_i:[0,1] \times [0,1] \to [0,1]$ be the conditional distribution function which summarizes the belief of player i about player $j \neq i$ (i's opponent) accepting a utility outcome, given player i's utility outcome, i = 1,2. Thus, $G_1(x_2|x_1)$ is player 1's assessment of the probability of player 2 accepting a utility outcome x_2 or less, given that player 1's utility outcome is x_1 .

The non-cooperative game we have in mind is the following. The underlying true bargaining problem HCW being given each player i announces a disagreement utility d_1 . The pair (H,d), $d=(d_1,d_2)$ is a fixed threat bargaining problem in W. Based on the information announced by the players the arbitrator using a solution F selects an outcome F (H,d) which each player accepts with a probability determined by G_1 and G_2 respectively. In the event that the outcome is rejected, by any one or both the players, the participants settle down for their true disagreement payoffs 0 = (0,0).

Let (d_1,d_2) (H be the announced disagreement payoffs of the respective players. If F is the solution being used by the arbitrator, the expected payoff of player 1 is

$$P_1(d_1,d_2) = F_1(H;d_1,d_2) \cdot G_1(F_2(H;d_1,d_2)) \cdot F_1(H;d_1,d_2)) \cdot$$

The expected payoff of player 2 is

$$P_2(d_1,d_2) = F_2(H_1d_1,d_2) \cdot G_2(F_1(H_1d_1,d_2)) \cdot F_2(H_1d_1,d_2)$$

Definition 5 :- A threat bargaining game with incomplete information equipped with a solution F is an ordered triplet (H_*F_*C) where

- (i) HCW is a true bargaining problem
- (11) $F : W \rightarrow R^2$ is a bargaining solution
- (iii) $G = (G_1, G_2)$ is a pair of conditional probability distribution functions on [0,1].

The notion of an equilibrium that we adopt in this paper is given by the following definition.

Definition 6: An equilibrium for a threat bargaining game with incomplete information equipped with a solution F, i.e. (H_*F_*G) is an ordered pair $(d_1^*, d_2^*) \in H$ such that

(i)
$$P_1(d_1,d_2) \gg P_1(d_1,d_2) + d_1 \in [0,1]$$

This is the femiliar Nash equilibrium which may dint of its self enforceability finds a distinguished placed as a solution concept. In the case of threat bargaining problems, the relationship between a Nash equilibrium and well known solutions to bargaining problems have been studied in Lahiri [1988, 1989 b].

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3. Main Theorem

In this section we shall try to impose conditions under which truthful revelation of disagreement utility will be guaranteed by a bargaining solution.

The main theorem of this paper is the following:

Theorem 1 s- Let
$$G_1(x_2 \mid x_1) = \min \{x_1, x_2\}$$
 if $x_1 > 0$

$$= 1 \qquad \text{if } x_1 = 0$$
and $G_2(x_1 \mid x_2) = \min \{x_1, x_2\}$ if $x_2 > 0$

$$= 1 \qquad \text{if } x_2 = 0$$

Then (0,0) is an equilibrium of the threat bargaining game with incomplete information (H_*F_*G) equipped with a solution F is and only if F is the Kalai-Smorodinsky [1975] solution i.e.

$$F(S) = \arg \max \left\{ \min \left(x_1, \varphi_{\bullet}(x_1) \right) \right\} = \arg \max \left\{ \min \left(x_2, \varphi_{\bullet}^{-1}(x_2) \right) \right\}$$

$$0 \not \perp x_1 \not \perp 1$$

$$0 \not \perp x_2 \not \perp 1$$

$$\forall S \vdash \overline{w}.$$

Proof :- Given
$$G_1$$
 and G_2 , $P_1(d_1,d_2) = \min \{F_1(H;d_1,d_2), \varphi_H(F_1(H;d_1,d_2))\}$

$$P_2(d_1,d_2) = \min \{F_2(H;d_1,d_2), \varphi_H(F_2(H;d_1,d_2))\}.$$

Observe that by property (i) of a solution $F_2(H;d_1,d_2) =$

$$\varphi_{H}(F_{1}(H;d_{1},d_{2})) = \text{And } F_{1}(H;d_{1},d_{2}) = \varphi_{H}^{-1}(F_{2}(H;d_{1},d_{2}))$$

Suppose $F = (F_1, F_2)$ is the Kalai-Smorodinsky [1975] solution.

 $P_{1}(H;0,0) = \min \left\{ F_{1}(H;0,0), \mathcal{J}_{H}(F_{1}(H;0,0)) \right\} \right\} \min \left\{ x_{1}, \mathcal{J}_{H}(x_{1}) \right\} \forall 0 \leq x_{1} \leq 1,$ by definition of the solution.

Since $P_1(H;d_1,0) = \min \{x_1, f_H(x_1)\}$ for some $x_1 \in [0,1]$, we get,

By a similar argument it follows that

$$P_2(H;0,0) \gg P_2(H;0,d_2) + d_2 \in [0,1]$$
.

Hence (0,0) is an equilibrium for (H.F.G).

Conversely suppose that (0,0) is an equilibrium for (H,F,G), but F is not the Kalai-Smorodinsky [1975] solution. Let $(x_1^{\sharp}, \mathcal{C}_H(x_1^{\sharp}))$ be the Kalai-Smorodinsky solution outcome for $H \in W$. By assumption (FUD) and without loss of generality $\int_{-\infty}^{\infty} d_1 \chi = 0$, such that

$$F(H;d_1^*,0) = (x_1^*,\varphi_H(x_1^*))$$

Hence

$$P_1(H;d_1,0) = \min \left\{ x_1^*, \mathcal{C}_H(x_1^*) \right\} > \min \left\{ F_1(H;0,0), \mathcal{C}_H(F_1(H;0,0)) \right\}$$

= $P_1(H;0,0)$,

contradicting that (0,8) is an equilibrium. Hence the theorem.

4. Conclusion :

Apart from achieving a characterization of the Kalai-Smorodinsky [1975] solution without a monotonicity assumption, we have also extended the framework of threat bargaining games and threat bargaining games with incomplete information, to include correlated beliefs in our model. This accounts for additional realism in our study.

The structure of the beliefs used to characterize the Kalai-Smorodinsky solution is not as straightforward as the uniform distribution used in characterizing the Nash [1950] solution [see Lahiri (1989 c)]. None the less it is a generated by a genuine distribution function and one that can arise very naturally in the presence of incomplete information.

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